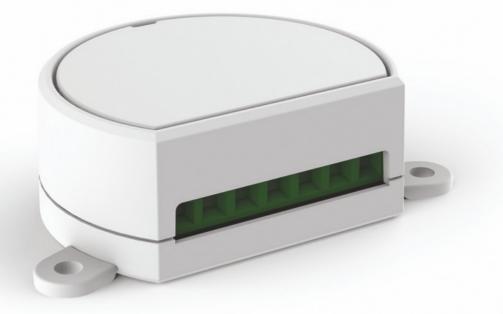
# **MCU-M500**

The product is an electronic control unit with UP, DOWN and STOP functions for managing 230 V, max. 500 W motors via wire and/or radio



linea



# INDEX

1 - PRODUCT FEATURES

1.1 - TECHNICAL DATA
2 - DESCRIPTION

2 - ELECTRICAL CONNECTIONS

2.1 - CONNECTION DIAGRAM

3 - USE OF THE CONTROL UNIT

1. USE VIA RADIO
2 - USE VIA WIRE

4 - CONTROL UNIT SETTINGS

CONFIGURATION OF BUTTONS VIA WIRE
CONFIGURATION OF MANOEUVRE TIMES

5 - RADIO PROGRAMMING MULTIFUNCTIONAL TRANSMITTERS

RADIO PROGRAMMING OF GENERIC TRANSMITTERS

# INDEX

- 1 PRODUCT FEATURES
  - 1.1 TECHNICAL DATA
  - 1.2 DESCRIPTION
- 2 ELECTRICAL CONNECTIONS
- 2.1 CONNECTION DIAGRAM 3 - USE OF THE CONTROL UNIT
  - 3.1 USE VIA RADIO
  - 3.2 USE VIA WIRE
- 4 CONTROL UNIT SETTINGS
  - 4.1 CONFIGURATION OF BUTTONS VIA WIRE
  - 4.2 CONFIGURATION OF MANOEUVRE TIMES
- **5 RADIO PROGRAMMING**
- **6 DELETION OF TRANSMITTERS**

## WARNINGS

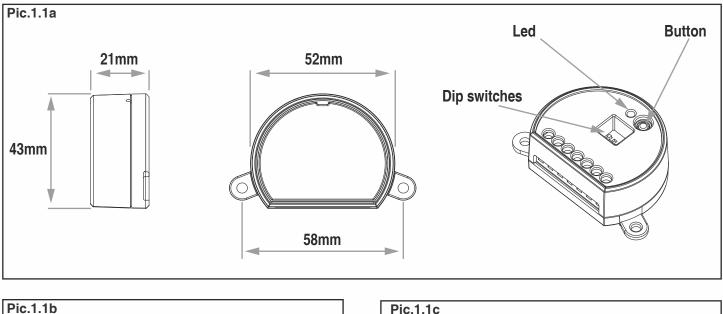
- Installation must be carried out only by qualified technicians in compliance with the electrical and safety standards in force.

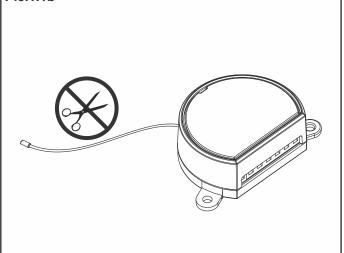
- All connections must be made with the power turned off.
- Use suitable cables.
- Do not cut through the aerial (see picture 1.1b)
- A suitably sized disconnection device must be set up on the electric power line that supplies the product.
- Disposal of waste materials must fully respect local standards.

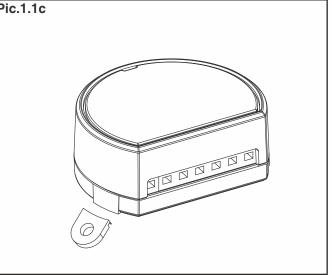
## **1 PRODUCT FEATURES**

## **1.1** TECHNICAL DATA

Power supply	From the grid 120-240 Vac
Outputs	1 motor powered from the grid:
	230V max 500W,
	110V max 250W
Num. of programmable transmitters	100
Radio frequency	433.920MHz ISM
Protection rating	IP20
Operating temperature	-20 +55 °C
Dimensions	52x43x21 mm







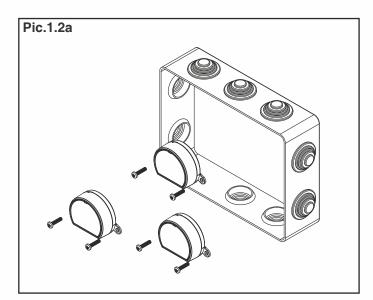
### **1.2** DESCRIPTION

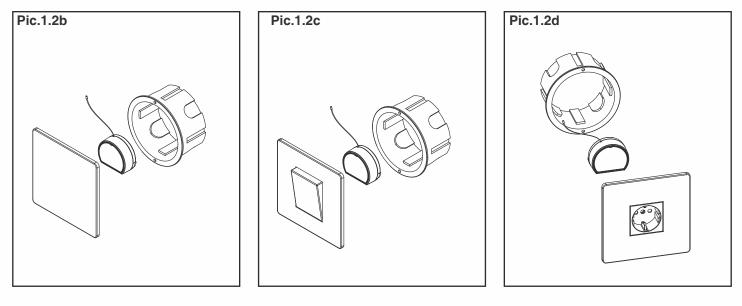
The product is a control unit to control electrical motors powered from the grid with power of max. 500 W (230 V) or max. 250 W (110 V).

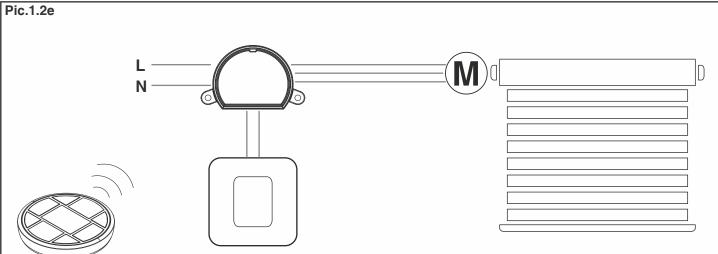
Ideal for activating motorised awnings, shutters and blinds with settable Up-Down-Stop, step and manual modes.

The ISM (industrial, scientific and medical) radio frequency band guarantees a long range, even through walls and ceilings.

Simple programming with dip-switches, reduced dimensions with breakable tabs (pic. 1.1c) for fixing with screws (pic. 1.2a) or for insertion into connection boxes up to 55 mm in diameter (pic. 1.2b, 1.2c and 1.2d).

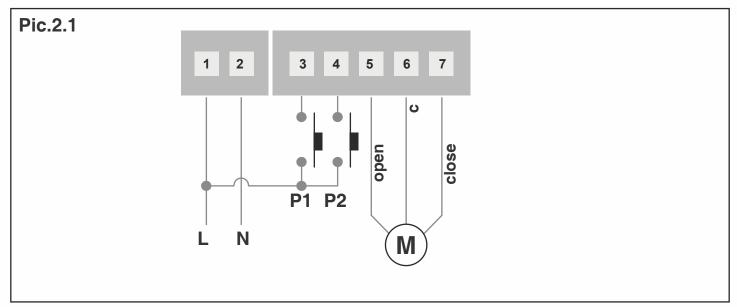






## **2 ELECTRICAL CONNECTIONS**

WARNING: It is possible to connect multiple buttons to the same input with parallel connection.



#### WARNING:

- The control unit is set up to control motors with internal end limit regulation.
- Buttons must be used for control via wire
- Multiple buttons or loads can be connected by using parallel cabling.

- If the condenser is not connected internally to the motor (typical of tubular motors), it is connected between the phases (terminals 4 and 6). Refer to the motor manual

- It is important to respect the opening and closing phase of the motor to make the commands of the transmitter and the wired inputs in mode 2 synchronise (see paragraph 4.1).

If the opening phase is not shown in the motor, carry out a test to check which wire it corresponds to.

## **3 USE OF THE CONTROL UNIT**

### **3.1** USE VIA RADIO

To control the motor via radio you must have compatible transmitters and therefore must carry out the association procedure; see paragraph 5.

The transmitter's command modes depend on the model used. If the transmitter is of a generic type, its operation depends on the way it is programmed (see paragraph 5, table 5.3a).

If the transmitter is multifunctional, refer to the transmitter manual, to the paragraph entitled "commands sent by the transmitter", bearing in mind that it is an "up-down-stop" device.

### **3.2** USE VIA WIRE

The device is set up to be able to accept commands via wire from buttons in terminals 3 and 4. Should you wish to control the load only via radio, it is not necessary to connect these devices for the control unit to work properly.

#### Default operation (Key P1 = Key P2):

DIP4 ON, step: with each press the motor will carry out an opening movement, a stop, a closing movement, a stop, in sequence.

DIP4 OFF, manual operation: the motor will carry out its manoeuvres only with the key pressed down. The motor will carry out an opening manoeuvre in sequence (when the key is released it will carry out a stop) and a closing manoeuvre (when the key is released it will carry out a stop).

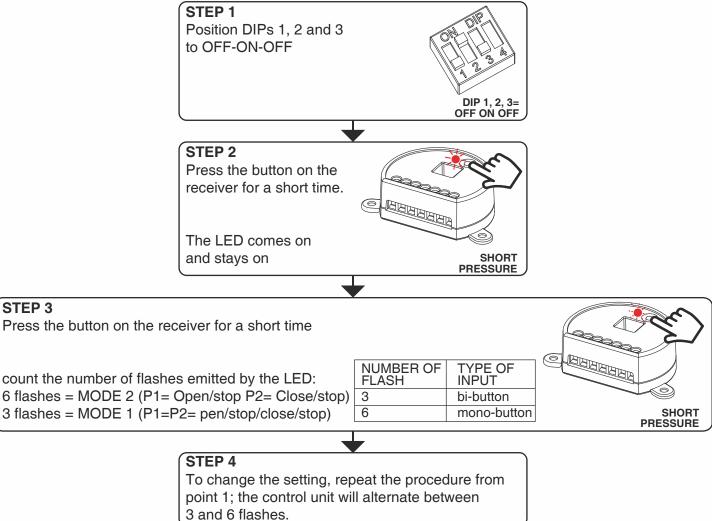
## **4 CONTROL UNIT SETTINGS**

### **4.1** CONFIGURATION OF BUTTONS VIA WIRE

Default: mode 1

This procedure lets you select the function of inputs "P1" (terminal 3) and "P2" (terminal 4). WARNING: the connected devices must be buttons.

#### **PROCEDURE:**



#### **CONTROL MODES:**

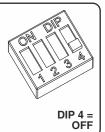
#### PULSE OPERATION

An action of the motor corresponds to each short pressure of the key



#### MANUAL OPERATION

The movements of the motor occur only with the key pressed down, when it is released the control unit carries out a stop

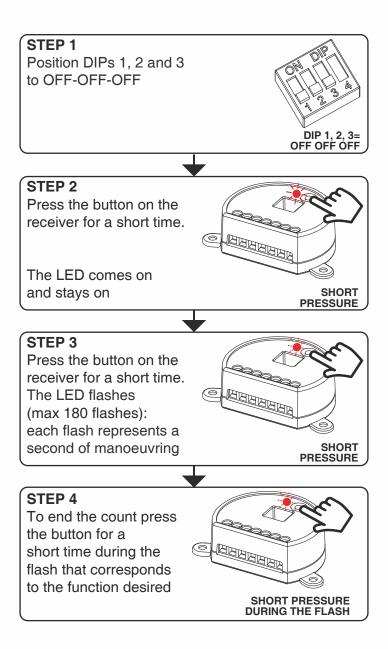


### **4.2** CONFIGURATION OF MANOEUVRE TIMES

Default: 60 seconds

This procedure is used to set the opening and closing manoeuvre time (maximum time that can be set 3 minutes).

#### **PROCEDURE:**



## **5 - RADIO PROGRAMMING**

This procedure lets you programme compatible multifunctional or generic transmitters.

#### WHICH REMOTE CONTROL DO YOU WANT TO ASSOCIATE WITH THE CONTROL UNIT?

### **MULTIFUNCTIONAL TRANSMITTERS**

#### CODES:

HB70-SLCT, HB70-SPCT, HB80-1C, HB80-1DIM, HB80-2L, HB80-30D, HB80-30RGBW, HB80-4C, HB80-4DIM, HB80-4L, HB90-6LT, ROUND-1SP, SENSA-M, SENSA-P, SENSA-R35M, SENSA-R35P, SENSA-R35T, SENSA-T, TOUCH-1, TOUCH-1CCT, TOUCH-1DIM, TOUCH-1SP, TOUCH-1L, TOUCH-1RGBW, TOUCH-3C, TOUCH-4DIM, TOUCH-CFU

With multifunctional transmitters the transmitter control modes depend on the model used. Refer to the transmitter manual, to the paragraph entitled "commands sent by the transmitter", bearing in mind that it is a "up/down/stop" device.

#### **GENERIC TRANSMITTERS (WIRELESS BUS)**

#### CODES:

HB80-6G, MCU-TX4, TOUCH-1G, TOUCH-2G, TOUCH-4G, TOUCH-LOCK4, TOUCH-TX2, ROUND-1G

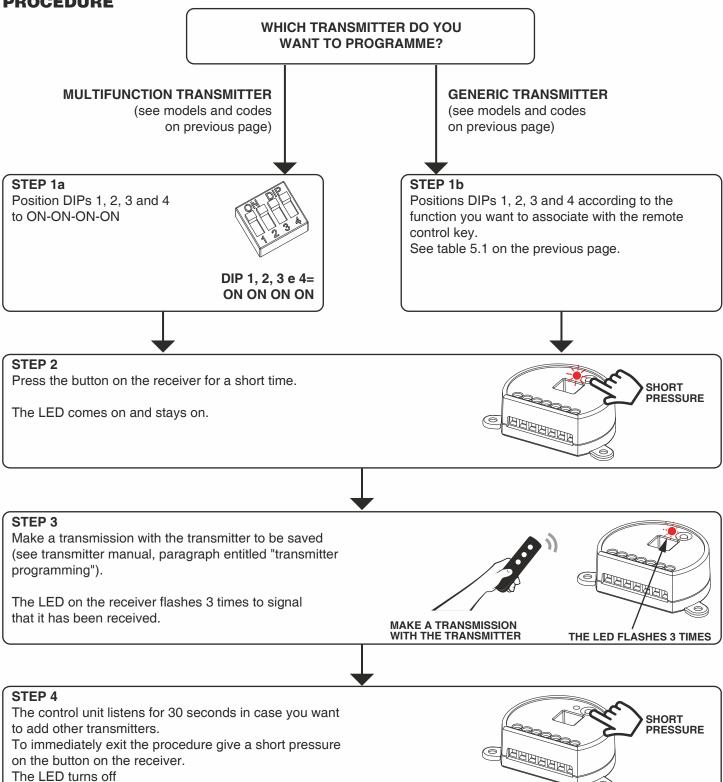
With generic transmitters, the transmitter's control modes depend on the function associated with the key during the association procedure.

The available function for the key are:

#### TABLE 5.1 - KEY FUNCTIONS OF THE GENERIC TRANSMITTER

POSITION OF DIP IN "STEP 1b" OF THE PROCEDURE	KEY FUNCTION
DIP : ON ON OFF	UP / STOP / DOWN / STOP
DIP : OFF ON ON	UP
DIP : ON OFF ON	DOWN
DIP : OFF OFF ON	STOP

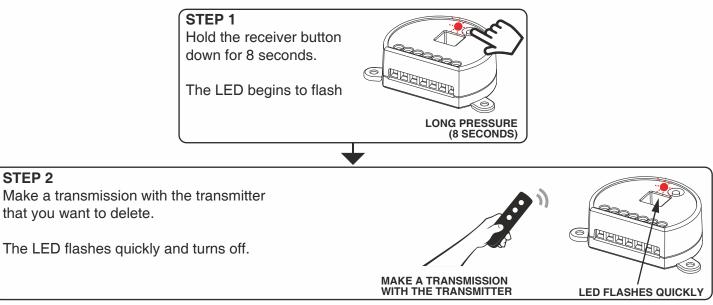




## **6 - DELETION OF TRANSMITTERS**

These procedures let you delete from the memory transmitters that have already been programmed.

### **6.1** DELETION OF SINGLE TRANSMITTER:



### **6.2** DELETION OF ALL THE SAVED TRANSMITTERS

